Why Imaging? Δ	Amag, <i>s</i> l	odetection)	Optimization	Validation	WFIRST Results	Future Work	⊨nd
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Why Imaging?	∆mag, <i>s</i>	P(detection)	Optimization	Validation	WFIRST Results	Future Work	End

With thousands of possible target stars and a limited amount of **time** on a future multi-billion dollar telescope How do we maximize the number of new exoplanets detected?



Why Imaging?	∆mag, <i>s</i>	P(detection)	Optimization	Validation	WFIRST Results	Future Work	End

Maximizing Exoplanet Detections of a Direct Imaging Mission

Dean Keithly







September 9, 2019

Why Imaging?	∆mag, <i>s</i> 00	P(detection) 0000	Optimization 00000000	Validation 0000000	WFIRST Results 0000	Future Work 000	End
Outline							



✓ Future Work

My contributions start here





- More transits (green) than other detections
- Imaging detects planets further from the host star

https://exoplanetarchive.ipac.caltech.edu/





https://exoplanetarchive.ipac.caltech.edu/

- More transits (green) than other detections
- Imaging detects planets further from the host star
- Imaging hasn't detected anything smaller than ≈Jupiter
- Earth-Like rocky bodies undiscovered



b₃, Star_ b, Image Plane – targ This is WFIRST: the observatory we will focus on.

(Marois et al. 2014)





Visual Magnitudes (mag)





10 / 53



Completeness, c_i , is the probability of detecting an exoplanet around a host star should a planet exist around that star



(Savransky et al., 2017)

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This is the background limiting Δmag

$$\Delta \text{mag}_{i}(t_{i}) = -2.5 \log_{10} \frac{SNR\sqrt{\frac{C_{b,i}}{t_{i}} + C_{sp,i}^{2}}}{C_{\mathscr{F}_{0}} 10^{-0.4v_{i}(\lambda)} T(\lambda, W\!A) \varepsilon_{PC}}$$

$$\begin{split} C_{b,i} &= ENF^2 \times (C_{sr,i} + C_{z,i} + C_{ez}) + (ENF^2 \times (C_{dc} + C_{cc}) + C_{rn}) \bullet \begin{array}{l} C_{b,i} \text{ - net background} \\ \text{count rate} \\ C_{sp,i} &= C_{sr,i} \times \varepsilon_{pp} \\ C_{sr,i} &= C_{\mathscr{F}_0} \times 10^{-0.4 \times v_i} \times \Psi(\lambda, WA) \times N_{pix} \\ \end{array}$$

• $C_{\mathcal{F}_0}$ - spectral flux density

λ = 565nm wavelength
 ν_i(λ) - target star B-V

• SNR = 5 - minimum required for detection • $\varepsilon_{PC} = 0.8$ - photon counting efficiency

color

(Nemati, 2014), (Nemati et al., 2017)

 $C_{\mathscr{F}_0}(\lambda) = \mathscr{F}_0(\lambda) A \Delta \lambda \varepsilon_a(\lambda) \varepsilon_{inst} \varepsilon_{syst}$



We now have a metric describing the "reward" for observing each star. We related the "reward" to the time "cost" of making that observation.

```
How do I determine integration time for each star, i in I(t_i)?
```

Why Imaging? Amag. s P(detection) Optimization Validation WFIRST Results Future Work End Reward & Cost Cost Image: Solution of the second sec

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```
How do I determine integration time for each star, i in I(t_i)?
```

We have a set of time constraints to consider:

- $T_{settling}$ time reserved for vibration damping, reaching thermal equilibrium, "digging the dark hole" (0.5d)
- T_{OH} time reserved for momentum dumping, orbit maintenance,

dark hole maintenance (0.5d)

 T_{max} - total mission time (30d)

Why Imaging? Amag. s P(detection) Optimization Validation WFIRST Results Future Work End Reward & Cost Cost Image: Solution of the second sec

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 T_{max} - total mission time (30d)

What is an initial feasible solution to the full non-linear optimization problem?

Why Imaging? 00	∆mag, <i>s</i> 00	P(detection) 0000	Optimization 0000000	Validation 0000000	WFIRST Results	Future Work 000	End
Optimizati	on: Part	1					

Algorithm 1: Binary Integer Program - $\mathbf{x}_1^* = BIP(\mathbf{c}_0, \mathbf{t}_0)$

Input: I, \mathbf{c}_0 , \mathbf{t}_0 , \mathcal{T}_{OH} , $\mathcal{T}_{settling}$, \mathcal{T}_{max} , and an optimization time limit maximum of 5 minutes

Output: \mathbf{x}_1^* , the list of binary values signaling to keep (1) or remove (0) each target

$$\begin{aligned} \mathbf{x}_{1}^{*} &= \arg\min_{\mathbf{x}} \quad -\sum_{i=0}^{N-1} x_{i} c_{0,i} \\ &\text{s.t.} \\ &\sum_{i \in \mathbf{I}} x_{i} (t_{0,i} + \mathcal{T}_{OH} + \mathcal{T}_{settling}) \leq \mathcal{T}_{max} \quad , \\ &x_{i} \in \{0,1\}, \qquad \forall \ i \ \in \mathbf{I} \end{aligned}$$

Coin-OR MIP - (Lougee-Heimer, 2003), (Savransky et al., 2017), (Keithly et al., 2019)

What is a <u>good</u> initial feasible solution to the full non-linear optimization problem?



Why Imaging? $\Delta mag, s$ P(detection) Optimization Validation Validation WFIRST Results Future Work End ooo Slope of Reward/Cost, $\varepsilon = dc/dt$

1. Assemble the expression and take the derivative w.r.t time

$$\varepsilon = \left. \frac{\mathrm{d}c_i}{\mathrm{d}t_i} \right|_{t_i} = \left. \frac{\mathrm{d}}{\mathrm{d}t_i} \left[\int_0^{\Delta \mathrm{mag}_i(t_i)} \int_{s_{\mathrm{min},i}}^{s_{\mathrm{max},i}} f_{\overline{s},\overline{\Delta \mathrm{mag}}}(s,\Delta \mathrm{mag}) \, \mathrm{d}s \, \mathrm{d}\Delta \mathrm{mag} \right] \right|_{t_i}$$

Why Imaging? $\Delta mag, s$ P(detection) Optimization Validation WFIRST Results Future Work ooo

1. Assemble the expression and take the derivative w.r.t time

$$\varepsilon = \left. \frac{\mathrm{d}c_i}{\mathrm{d}t_i} \right|_{t_i} = \left. \frac{\mathrm{d}}{\mathrm{d}t_i} \left[\int_0^{\Delta \mathrm{mag}_i(t_i)} \int_{s_{\mathrm{min},i}}^{s_{\mathrm{max},i}} f_{\overline{s},\overline{\Delta \mathrm{mag}}}(s,\Delta \mathrm{mag}) \, \mathrm{d}s \, \mathrm{d}\Delta \mathrm{mag} \right] \right|_{t_i}$$

2. Multiply by $d\Delta \text{mag}_i/d\Delta \text{mag}_i$

$$= \frac{\mathrm{d}}{\mathrm{d}\Delta\mathrm{mag}_{i}} \left[\int_{0}^{\Delta\mathrm{mag}_{i}(t_{i})} \int_{s_{\mathrm{min},i}}^{s_{\mathrm{max},i}} f_{\overline{s},\overline{\Delta\mathrm{mag}}}(s,\Delta\mathrm{mag}) \,\mathrm{d}s \,\mathrm{d}\Delta\mathrm{mag} \right] \left. \frac{\mathrm{d}\Delta\mathrm{mag}_{i}}{\mathrm{d}t_{i}} \right|_{t_{i}}$$

End

Slope of Reward/Cost, $\varepsilon = dc/dt$

1. Assemble the expression and take the derivative w.r.t time

Optimization

$$\varepsilon = \left. \frac{\mathrm{d}c_i}{\mathrm{d}t_i} \right|_{t_i} = \left. \frac{\mathrm{d}}{\mathrm{d}t_i} \left[\int_0^{\Delta \mathrm{mag}_i(t_i)} \int_{s_{\mathrm{min},i}}^{s_{\mathrm{max},i}} f_{\overline{s},\overline{\Delta \mathrm{mag}}}(s,\Delta \mathrm{mag}) \, \mathrm{d}s \, \mathrm{d}\Delta \mathrm{mag} \right] \right|_{t_i}$$

2. Multiply by $d\Delta \text{mag}_i/d\Delta \text{mag}_i$

$$= \frac{\mathrm{d}}{\mathrm{d}\Delta\mathrm{mag}_{i}} \left[\int_{0}^{\Delta\mathrm{mag}_{i}(t_{i})} \int_{s_{\mathrm{min},i}}^{s_{\mathrm{max},i}} f_{\overline{s},\overline{\Delta\mathrm{mag}}}(s,\Delta\mathrm{mag}) \, \mathrm{d}s \, \mathrm{d}\Delta\mathrm{mag} \right] \left. \frac{\mathrm{d}\Delta\mathrm{mag}_{i}}{\mathrm{d}t_{i}} \right|_{t_{i}}$$

WFIRST Results

3. Apply Fundamental Theorem of Calculus

$$= \left[\int_{s_{\min,i}}^{s_{\max,i}} f_{\overline{s},\overline{\Delta \max}}(s,\Delta \max(t_i)) \, \mathrm{d}s \right] \left. \frac{\mathrm{d}\Delta \max_{i}}{\mathrm{d}t_i} \right|_{t}$$

Future Work

End

Slope of Reward/Cost, $\varepsilon = dc/dt$

1. Assemble the expression and take the derivative w.r.t time

Optimization

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$$\varepsilon = \left. \frac{\mathrm{d}c_i}{\mathrm{d}t_i} \right|_{t_i} = \left. \frac{\mathrm{d}}{\mathrm{d}t_i} \left[\int_0^{\Delta \mathrm{mag}_i(t_i)} \int_{s_{\mathrm{min},i}}^{s_{\mathrm{max},i}} f_{\overline{s},\overline{\Delta \mathrm{mag}}}(s,\Delta \mathrm{mag}) \, \mathrm{d}s \, \mathrm{d}\Delta \mathrm{mag} \right] \right|_{t_i}$$

2. Multiply by $d\Delta \text{mag}_i/d\Delta \text{mag}_i$

$$= \frac{\mathrm{d}}{\mathrm{d}\Delta\mathrm{mag}_{i}} \left[\int_{0}^{\Delta\mathrm{mag}_{i}(t_{i})} \int_{s_{\mathrm{min},i}}^{s_{\mathrm{max},i}} f_{\overline{s},\overline{\Delta\mathrm{mag}}}(s,\Delta\mathrm{mag}) \, \mathrm{d}s \, \mathrm{d}\Delta\mathrm{mag} \right] \left. \frac{\mathrm{d}\Delta\mathrm{mag}_{i}}{\mathrm{d}t_{i}} \right|_{t_{i}}$$

Validation

3. Apply Fundamental Theorem of Calculus

$$= \left[\int_{s_{\min,i}}^{s_{\max,i}} f_{\overline{s},\overline{\Delta mag}}(s,\Delta mag(t_i)) \, \mathrm{d}s \right] \left. \frac{\mathrm{d}\Delta mag_i}{\mathrm{d}t_i} \right|_{t_i}$$

$$\frac{\mathrm{d}\Delta\mathrm{mag}_{i}}{\mathrm{d}t_{i}}\left(t_{i}\right) = \frac{5C_{b,i}}{4\ln(10)}\frac{1}{C_{b,i}t_{i}+\left(C_{sp,i}t_{i}\right)^{2}}$$

From (Nemati, 2014)

WFIRST Results

Future Work

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End

Why Imaging? Amag. s P(detection) Optimization Validation WFIRST Results Future Work End Optimization: Part 2

Algorithm 2: Bounded Scalar Minimization Wrapping Binary Integer Program

- **Input:** I, C_{p0} , C_{b0} , C_{sp0} , T_{OH} , $T_{settling}$, T_{max} , and an optimization time limit maximum of 5 minutes
- **Output:** ε^* , the value of dc/dt evaluated for each target which maximizes yield **Output:** t^* , integration times for each target evaluated at ε^*
- **Output:** \mathbf{x}_2^* , the list of binary values signaling to keep or remove each target

$$\begin{split} \varepsilon^* &= \arg\min_{\varepsilon} \quad -\sum_{i \in I} \operatorname{BIP}(c_i(t_i^*(\varepsilon)), t_i^*(\varepsilon), T_{OH}, T_{settling}, T_{max})_i c_i(t_i^*(\varepsilon)) \\ &\text{s.t.} \\ &\varepsilon \leq 7, \\ &-\varepsilon \leq 0 \end{split}$$

$$\begin{array}{l} \mathbf{t}_{2}^{*} \leftarrow [t_{i}^{*}(\boldsymbol{\varepsilon}^{*}), \ \forall \ i \in \mathbf{I}] \\ \mathbf{x}_{2}^{*} \leftarrow [\mathsf{BIP}(c_{i}(t_{i}^{*}(\boldsymbol{\varepsilon}^{*})), t_{i}^{*}(\boldsymbol{\varepsilon}^{*}), T_{OH}, T_{settling}, T_{\max}), \ \forall \ i \in \mathbf{I}] \end{array}$$

(Savransky et al., 2017), (Keithly et al., 2019)

Why Imaging? 00	∆mag, <i>s</i> 00	P(detection) 0000	Optimization 00000000	Validation 0000000	WFIRST Results	Future Work 000	End
Optimizat	ion: Part	t 3					

Algorithm 3: SLSQP Optimization

t

Input: I, \mathbf{f}_{Z} , \mathbf{t} , T_{OH} , $T_{settling}$ and T_{max} **Output:** \mathbf{t}_{3}^{*} , the integration times to spend on each star

$$\begin{aligned} * &= \arg \min_{\mathbf{t}} -\sum_{i=0}^{N-1} c_i(t_i) \\ \text{s.t.} \\ & t_i < T_{\max}, \quad \forall \ i \in \mathbf{I}, \\ -t_i < 0, \qquad \forall \ i \in \mathbf{I}, \\ \sum_{i \in \mathbf{I}} x_i(T_{OH} + T_{settling}) + t_i < T_{\max} \end{aligned}$$

Scipy SLSQP - (Boggs and Tolle, 1995), (Savransky et al., 2017), (Keithly et al., 2019)







Why Imaging?	∆mag, <i>s</i> 00	P(detection) 0000	Optimization 00000000	Validation ●○○○○○○	WFIRST Results 0000	Future Work 000	End
EXOSIMS							



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Why Imaging? Amag. s P(detection) Optimization Validation WFIRST Results Future Work End Keep-out Regions Construction <

Problem: Sensors saturate when looking at bright objects

Solution: Designate regions the telescope is not allowed to look at



Why Imaging?	∆mag, <i>s</i>	P(detection)	Optimization	Validation	WFIRST Results	Future Work	End
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Keep-out	Map						



(Soto et al., 2019)

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Why Imaging?	∆mag, <i>s</i>	P(detection)	Optimization	Validation	WFIRST Results	Future Work	End
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Keep-out	Map						



(Soto et al., 2019)

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Zodiacal I	_ight						







- Red dots linear interpolant minimums for each latitude
- 15d deviation from minimum has marginal value change

(Leinert et al., 1998)





- Red dots linear interpolant minimums for each latitude
- 15d deviation from minimum has marginal value change

Idea! lets make observations at minimums!

(Leinert et al., 1998)

Why Imaging?	∆mag, <i>s</i> 00	P(detection) 0000	Optimization 00000000	Validation ○○○●○○	WFIRST Results	Future Work 000	End
Zodiacal	Light						



- Red dots linear interpolant minimums for each latitude
- 15d deviation from minimum has marginal value change
 - Idea! lets make observations at minimums!
- Black dots implemented observations

< A

(Leinert et al., 1998) -





Why Imaging? Amag, s P(detection) Optimization Validation Optimization Optimization



- All planets detected in WFIRST <u>all</u> simulations (purple)
- WFIRST might detect $\approx 2R_{\oplus}$ planets
- WFIRST is likely to detect planets with $0.5AU \le s \le 5AU$

https://exoplanetarchive.ipac.caltech.edu/

Why Imaging? 00	∆mag, <i>s</i> 00	P(detection) 0000	Optimization 00000000	Validation 0000000	WFIRST Results	Future Work 000	End
Mean Un	ique Det	ections					

Unique DetectionsPlanet PopulationCompletenessKepler LikeSAG 13Kepler Like5.484SAG13

The summed completeness of the planned observation list was 2.31. Multiplying by the planet occurrence rate (2.375) predicts 5.48 detections will be made.

Why Imaging? 00	∆mag, <i>s</i> 00	P(detection)	Optimization 00000000	Validation 0000000	WFIRST Results ○●○○	Future Work 000	End
Mean Uni	que Dete	ections					

Unique DetectionsPlanet PopulationCompletenessKepler LikeSAG 13Kepler Like5.48416.266

The summed completeness of the planned observation list was 2.31. Multiplying by the planet occurrence rate (2.375) predicts 5.48 detections will be made.

Why Imaging?	∆mag, <i>s</i>	P(detection)	Optimization	Validation	WFIRST Results	Future Work	End
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Mean Un	ique Det	ections					

Unique DetectionsPlanet PopulationCompletenessKepler LikeSAG 13Kepler Like5.48416.117SAG135.20616.266

The summed completeness of the planned observation list was 2.31. Multiplying by the planet occurrence rate (2.375) predicts 5.48 detections will be made.

Why Imaging?	∆mag, <i>s</i>	P(detection)	Optimization	Validation	WFIRST Results	Future Work	End
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Mean Uni	que Dete	ections					

Unique	e Detections		# C	# Characterizations			
	Planet Pop	oulation	Planet Population				
Completeness	Kepler Like	SAG 13	Completeness	Kepler Like	SAG 13		
Kepler Like	5.484	16.117	Kepler Like	0.214	1.003		
SAG13	5.206	16.266	SAG13	0.217	0.718		

The summed completeness of the planned observation list was 2.31.

Multiplying by the planet occurrence rate (2.375) predicts 5.48 detections will be made.

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Why Imaging?	∆mag, <i>s</i>	P(detection)	Optimization	Validation	WFIRST Results	Future Work	End
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Summary							

- Target list optimization method
- 2 $\sum c$ planned $\approx \sum c$ implemented
- **③** Target t_i distribution on sky is uneven
- **③** WFIRST can detect unique planets in R_p vs a space
- SEXOSIMS simulates universes, validates the planned target list
- Optimizing with Kepler-Like population is preferred
- **Optimizing with Kepler-Like leads to detections of smaller** R_p planets
- **③** WFIRST can detect planets in the regime between "imaging" and "transits"
- $\textcircled{0} \ \ {\rm Running \ 1000x \ simulations} \rightarrow \approx 3\% \ \ {\rm uncertainty}$
- **WFIRST** can detect \approx 5.48 exoplanets in a blind-search survey

Why Imaging? 00	∆mag, <i>s</i> 00	P(detection) 0000	Optimization 00000000	Validation 0000000	WFIRST Results	Future Work ●0○	End
HabEx							



- HabEx is one of 4 future flagship telescope concepts
- Designed to image exo-Earths







- All planets detected in HabEx simulations (purple)
- HabEx might detect $\approx R_{\oplus}$ at 1AU
- "lines" are limits of simulated planets

https://exoplanetarchive.ipac.caltech.edu/

Why Imaging? 00	∆mag, <i>s</i> 00	P(detection) 0000	Optimization 00000000	Validation 0000000	WFIRST Results	Future Work ○○●	End
Future Wo	ork						

Detecting and Characterizing Earth-Like Exoplanets, Revisiting targets, Characterizing Orbits

- Dynamic program rewarding only confirmed & characterized Earth-Like planets
- $P(planet type|s_0, \Delta mag_0)$ what is the probability a detected planet is of a given planet type?
- $P(s_1, \Delta mag_1, \theta_1 | planet type, MET + \Delta t, s_0, \Delta mag_0)$ when is the earliest I can take my next image?
- simulating stable star systems
- Decompose completeness by planet-type
- Decompose dynamic-completeness by planet type

Why Imaging?	∆mag, <i>s</i>	P(detection)	Optimization	Validation	WFIRST Results	Future Work	End
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Contributi	ons						

Journal Publications:

- [1] Keithly D., et al., (2018) "A cephalopod-inspired combustion powered hydro-jet engine using soft actuators." Extreme Mechanics Letters.
- [2] Keithly D., et al., (In Review) "Optimal Scheduling of Exoplanet Direct Imaging Single-Visit Observations of a Blind Search Survey." Journal of Astronomical Telescopes, Instruments, and Systems.

Conference Presentations:

- [1] Keithly D., et al., (2019) "Blind Search Single-Visit Exoplanet Direct Imaging Yield for Space Based Telescopes." American Astronomical Society Meeting 233.
- [2] Keithly D., et al., (2018) "Scheduling and target selection optimization for exoplanet imaging spacecraft." International Society for Optics and Photonics.
- [3] Keithly D., et al., (2018) "WFIRST: Exoplanet Target Selection and Scheduling with Greedy Optimization." American Astronomical Society Meeting 231.
 Code Contribution: github.com/dsavransky/EXOSIMS
 Report: Savransky et al., (2019) "Modular Active Self-Assembling Space Telescope

Swarms," NIAC - Future conference paper (Mirro Force Opt.)

Why Imaging?	∆mag, <i>s</i>	P(detection)	Optimization	Validation	WFIRST Results	Future Work	End
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Coursewo	rk						

Completed: SYSEN 5400 **SYSEN 5100** MAE 5160 MAE 6060 **SYSEN 5200** MAE 5730 MAE 5780 MAE 6700 **ASTRO 6525** MAE 6720 **ORIE 6125 ORIE 5300 ORIE 5310**

Future:

Multivariable Control Celestial Mechanics Global Positioning System

- System Architecture
- Model Based Systems Engineering
- Spacecraft Technology & Systems
- Spacecraft Dynamics, Estimation, & Control
- Analysis Behavior & Optimization
- Intermediate Dynamics & Vibrations
- Feedback Control Systems
- Advanced Dynamics
- Optical, Infrared, and Sub-millimeter Telescopes
- Celestial Mechanics
- Computational Methods in Operation Research
- Optimization I
- Optimization II

Super Aw	vesome S	Side-Work					
Why Imaging?	∆mag, <i>s</i>	P(detection)	Optimization	Validation	WFIRST Results	Future Work	End

Internships: Marshall SpaceFlight Center2015Jet Propulsion Lab2016Jet Propulsion Lab2017Jet Propulsion Lab2017Jet Propulsion Lab2018Procedural Thermal Model GenerationAir Force Research Lab2019Ball Aerospace?2020GOAL	e Conference e Conference
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Extra:

SPLASH	2018-19	Teaching Space Classes (obviously)
FIRST	2018	FRC 5254 Trumansburg

Acknowledgements				000000	0000	000	
Why Imaging?	$\Delta mag, s$	P(detection)	Optimization	Validation	WFIRST Results	Future Work	End

- NASA's NAIF planetary data system kernels.
- Washington Double Star Catalog maintained at the U.S. Naval Observatory.
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- NASA Exoplanet Archive, operated by California Institute of Technology, under contract with the National Aeronautics and Space Administration under the Exoplanet Exploration Program, and from the SIMBAD database, operated at CDS, Strasbourg, France.
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54 / 53

Constructing Joint Probability Distributions: Kepler Like

$$f_{\bar{a}}(a) = \frac{a^{-0.62}}{a_{\text{norm}}} \exp\left(-\frac{a^2}{a_{\text{knee}}^2}\right)$$
$$a_{\text{norm}} = \int_{a_{\text{min}}}^{a_{\text{max}}} a^{-0.62} \exp\left(-\frac{a^2}{a_{\text{knee}}^2}\right) da$$
$$a_{\text{min}} = 0.1 \text{ AU}$$
$$a_{\text{max}} = 30 \text{ AU}$$



$$SNR = \frac{r_{pl}t}{\sqrt{r_{noise}t + \sigma_{spstr}^2}}$$

$$r_{pl} - \text{Electron count rate from the planet}$$

$$r_{noise} - \text{noise "rate" from planet, speckle, zodi, exo-zodi, DC, CIC, RN}$$

$$\sigma_{spstr} - \text{variance of the residual speckle structure}$$

$$ENF - \text{Excess Noise Factor caused by signal gain}$$

WFIRST Optics: Shaped pupil coronagraph



Image Credit: Jeremy Kasdin 2014

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Image Credit: Jeremy Kasdin 2014

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$$\mathscr{F}_{0}(\lambda) = 10^{4} imes 10^{(4.01 - rac{\lambda - 550 nm}{770 nm})} ph/s/m^{2}/nm$$

Core Throughput



Core Mean Intensity



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Image courtesy of NASA

Planet Occurrence Rates



Figure 7. Average number of planets per size bin for main-sequence FGKM stars, determined here from the Q1–Q6 *Kepler* data and corrected for false

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Orbital Elements to **r**

Table: Caption

$$\begin{bmatrix} x_1 & x_2 & x_3 \\ y_1 & y_2 & y_3 \\ z_1 & z_2 & z_3 \end{bmatrix} = \begin{bmatrix} \cos \omega & \sin \omega & 0 \\ -\sin \omega & \cos \omega & 0 \\ 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos l & \sin l \\ 0 & -\sin l & \cos l \end{bmatrix} \cdot \begin{bmatrix} \cos O & \sin O & 0 \\ -\sin O & \cos O & 0 \\ 0 & 0 & 1 \end{bmatrix}$$
After expanding

Kepler-Like: Modified power-law distribution for semi-major axis (a) of the form

$$f_{\overline{a}}(a) = \frac{a^{-0.62}}{a_{\text{norm}}} \exp\left(-\frac{a^2}{a_{\text{knee}}^2}\right)$$
(1)

where -0.62 is adopted from refnumMoorhead2011 derived from the power law fit from refnumCumming2008.

In this model, we include an exponential decline in semi-major axis past a "semi-major axis knee" ($a_{\rm knee}$), which we place at 10 AU, based on the observed, sharp decline in detected planets with period $\approx 10^4$ d around an assumed solar mass star (Cumming et. al. 2008). The normalization factor is given by the integrating the un-normalized distribution over a specific *a* range

$$a_{\text{norm}} = \int_{a_{\text{min}}}^{a_{\text{max}}} a^{-0.62} \exp\left(-\frac{a^2}{a_{\text{knee}}^2}\right) \mathrm{d}a, \qquad (2)$$

where we consider values of *a* range in $a_{\min} = 0.1$ AU to $a_{\max} = 30$ AU, again based on the paucity of wide-separation planets discovered to date. We note, however, that for WFIRST, which has an inner working angle (IWA) of 0.15 arcsec, the closest target list star has distance, d_i , of 2.63 pc and would have the $a_{66/53}$ 1. The goal of direct detection is to spatially separate the exo- planet light from that of its primary. This affords access to exo- planet atmospheres, which yields fundamental information including effective temperature, gravity, atmospheric composi- tion and abundances, orbital motion, and perhaps even weather and and planetary spin. 2. The goal of direct imaging is to assem- ble the first statistically significant sample of exoplanets that probes beyond the reach of indirect searches and quantifies the abundance of solar systems like our own. (McBride et al., 2011)Read Section 1 of McBride2011 for all other scientific motivation.

A significant orbital eccentricity effects a planet's climate (i.e. equilibrium temperature, amplitude of seasonal variability and potentially its habitability due to variations in the incident stellar flux) (Moorhead et al., 2011) From Williams and Pollard 2002, Gaidos and Williams 2004

dMag vs s of Different Solar System Planets

EXTRA

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