## How orbital fit uncertainties impact dynamic scheduling Corey Spohn<sup>1</sup>, Dmitry Savransky<sup>1,2</sup>

<sup>1</sup>Sibley School of Mechanical and Aerospace Engineering, Cornell University, Ithaca, NY, United States <sup>2</sup>Carl Sagan Institute, Cornell University, Ithaca, NY, United States

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CARL SAGAN

Introduction					
To increase the number of detections future direct imaging mis-					
sions are planning to observe many planets that have been ob-					
served by radial velocity (RV) instruments already. Planets known					
based on RV measurements will have orbital fits of varying accu-					
racy depending on the measurement error. Current state of the art					
can observe with a precision of approximately 1 m/s on RV mea-					
surements. To fit a terrestrial planet the RV precision needs to be					
improved because the RV signiatures are only tens of centimeters					
in amplitude. As the precision increases orbital fits will improve,					
but a radial velocity fit cannot provide all of the keplerian param-					
eters necessary to simulate an observation. Here we examine the					

cost of poor orbital fits on scheduling direct imaging observations.

## Synthetic RV data

• The RV plots shown below were created using on the following superearth parameters

Parameter	Value	Unit
Semi-major axis $a$	1.5	AU
Eccentricity $e$	0.198	
Inclination $i$	90	Degrees
Planet mass $M_p$	1.5	$M_\oplus$
Planet radius $R_p$	1.12	$R_\oplus$
Argument of periastron $\omega_p$	4.14	Radians
Distance from observer $d$	10	Parsecs

## How RV fits spread out visually

These plots show how the "RV fit cloud" population disperses in time in the flux ratio (ratio of planet brightness to star brightness) vs separation (angular distance between the star and planet) space The star represents the synthetic planet's actual flux ratio and separation

2010.00, after 0 periods		2010.00, after 0 periods	
10 cm/s error	10	1 cm/s error	- 1.0
			- 0.9
			- 0.8
			- 0.7
	tio		- 0.6
	ени 10 <sup>-9</sup> . Х		- 0.5





i failet 5 arguillette	$\sqrt{c}\cos\omega_s, \sqrt{c}\sin\omega_s$	$\omega_s = \arctan\left(\sqrt{e}\cos(\omega_s)\right)$
of periastron, $\omega_p$		$\omega_p = \omega_s + \pi$
Time of periastron, $T_p$	$T, e, \omega_s, T_c$	$\nu_p = \pi/2 - \omega_s$
		$\tan\left(\frac{E}{2}\right) = \sqrt{\frac{1-e}{1+e}} \tan\left(\frac{\nu}{2}\right)$
		$M = E - e\sin E$
		$T_p = T_c - \frac{MT}{2\pi}$
$M_p \sin i$	K, T, e	$M_p \sin i = \left(\frac{T}{2\pi G}\right)^{\frac{1}{3}} K M_s^{\frac{2}{3}} \sqrt{1 - e^2}$
	•	

sample those parameters separately

as a white line and the simulated observations as blue points.

vide false confidence

Detection of ExoplanetsIX, S. B. Shaklan, ed.,11117, p. 51, SPIE, sep 2019. [3] "The Habitable Exoplanet Observatory (HabEx) Mission Concept Study Final Report," 2020.

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Contact

Corey Spohn - cas584@cornell.edu



Estimating probability of detection

• Our goal is to estimate when a planet will be visible to an observatory, or when the planet is within the observatory's field of view and bright enough. Number of currently visible planets in population Probability of detection =Number of planets in population • The visibility was based off of HabEx [3]



Credible interval

parameter in the

RV fit cloud

for the fitting basis

parameters from the

