

7 - Towards General Perturbations

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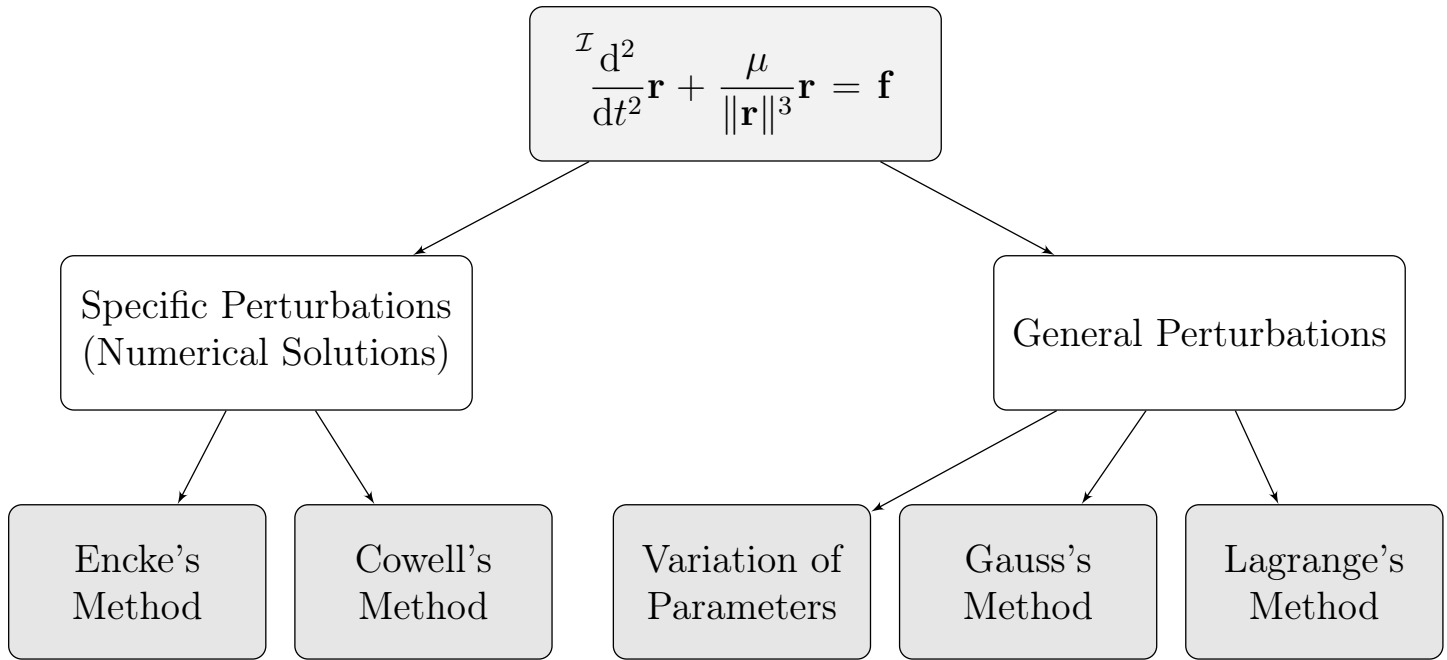
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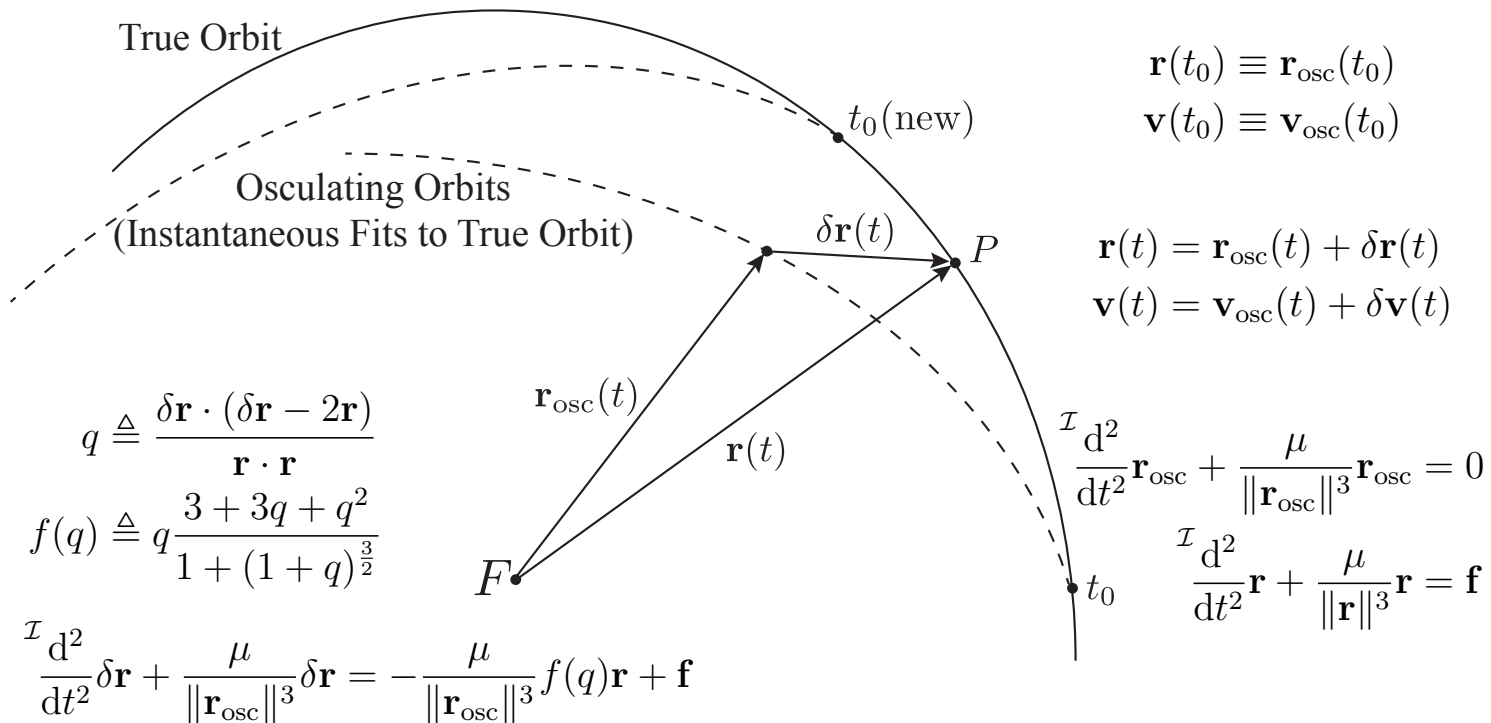
Towards General Perturbations

We will continue our journey towards a completely general description of perturbations of two-body orbits by first considering specific numerical solutions to perturbed systems, and then developing a complete force-based description of perturbations in the form of Gauss's perturbation equations. Along the way, we will introduce an incredibly important piece of mathematical formalism (the Legendre polynomials, which will play a huge role throughout the rest of the course) as well as the concept of the sphere of influence, which is a key tool in preliminary interplanetary trajectory design.

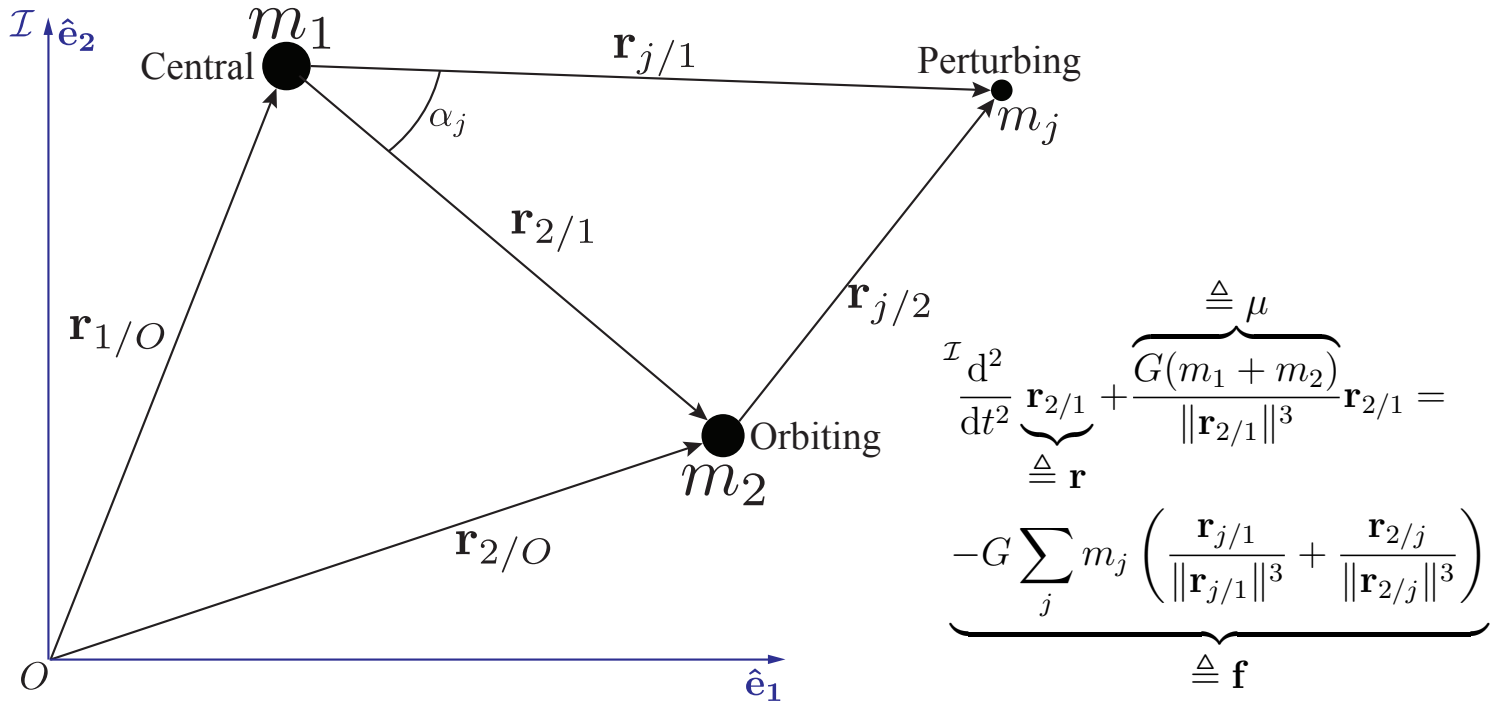
Perturbations Roadmap



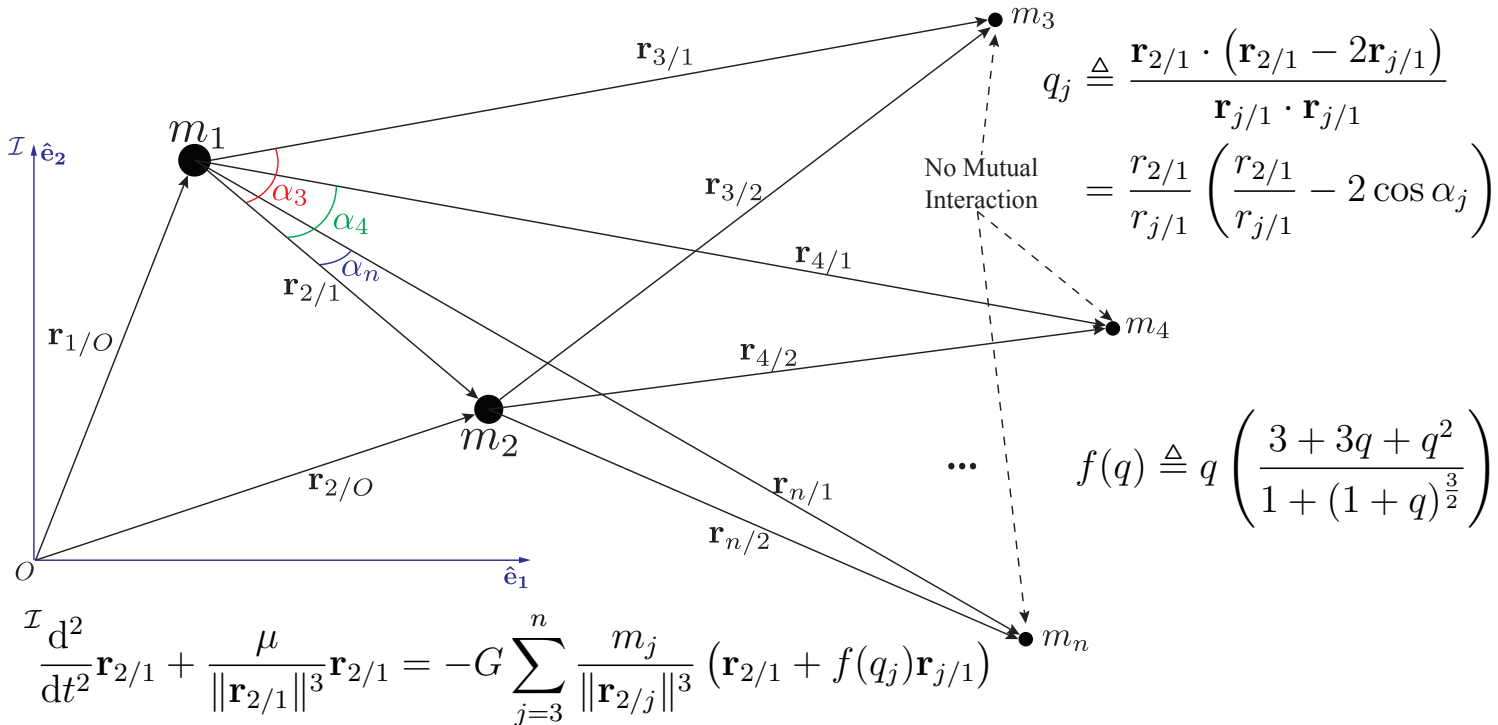
Encke's Method



3rd (Nth) Body Perturbations



Cowell's Method



The Disturbing Function

$$\mathcal{I} \frac{d^2}{dt^2} \mathbf{r}_{2/1} + \frac{\mu}{\|\mathbf{r}_{2/1}\|^3} \mathbf{r}_{2/1} = -G \sum_j m_j \left(\frac{\mathbf{r}_{j/1}}{\|\mathbf{r}_{j/1}\|^3} + \frac{\mathbf{r}_{2/j}}{\|\mathbf{r}_{2/j}\|^3} \right) = \nabla \sum_{j=3}^n R_j$$

$$R_j \triangleq Gm_j \left(\frac{1}{r_{2/j}} - \frac{1}{r_{j/1}^3} \mathbf{r}_{2/1} \cdot \mathbf{r}_{j/1} \right) = \frac{Gm_j}{r_{j/1}} \left(\frac{r_{j/1}}{r_{2/j}} - \nu_j x_j \right)$$

$$x_j \triangleq \frac{r_{2/1}}{r_{j/1}} \quad \nu_j \triangleq \cos \alpha_j = \frac{\mathbf{r}_{2/1} \cdot \mathbf{r}_{j/1}}{r_{2/1} r_{j/1}} \quad q_j = x_j^2 - 2\nu_j x_j$$

$$\frac{r_{j/1}}{r_{2/j}} = (1 + q_j)^{-\frac{1}{2}} = \sum_{k=0}^{\infty} \sum_{l=0}^{\lfloor \frac{k}{2} \rfloor} \frac{(-1)^l (2k - 2l)!}{2^k l! (k - l)! (k - 2l)!} \nu_j^{k-2l} x_j^k = \sum_{k=0}^{\infty} P_k(\nu_k) x_j^k$$

A Brief Review of Legendre Polynomials

- Legendre Polynomials are solutions to Legendre's Differential Equation:

$$\frac{d}{dx} \left((1 - x^2) \frac{d}{dx} P_n(x) \right) + (n^2 - n) P_n(x) = 0$$

- Rodrigues Formula:

$$P_k(\nu) = \frac{1}{2^k k!} \frac{d^k}{d\nu^k} (\nu^2 - 1)^k = \frac{1}{2^k} \sum_{n=0}^k \binom{k}{n}^2 (\nu - 1)^{k-n} (\nu + 1)^n$$

- Generating Function: $L(x, \nu) \triangleq (1 - 2\nu x + x^2)^{-1/2} = \sum_{k=0}^{\infty} P_k(\nu) x^k$

- Properties: $P_k(-\nu) = (-1)^k P_k(\nu)$ $P_k(1) = 1$ $P_k(-1) = (-1)^k$

- Recurrence Formulas: $kP_k(\nu) - (2k - 1)\nu P_{k-1}(\nu) + (k - 1)P_{k-2}(\nu) = 0$

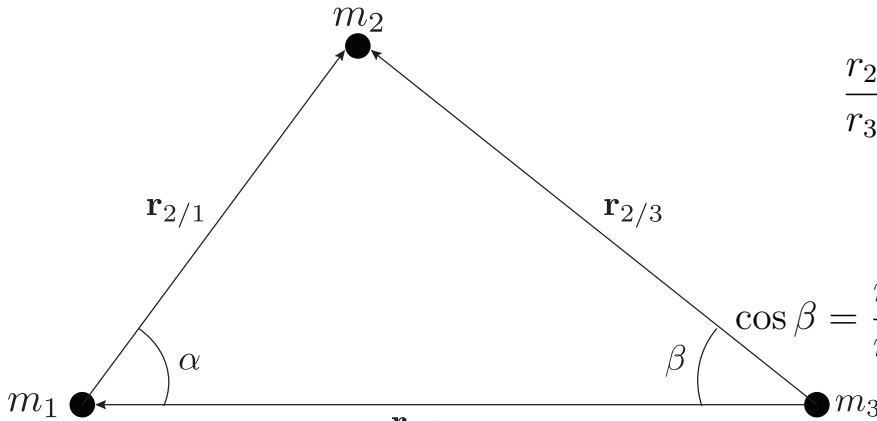
$$\left. \begin{aligned} kP_k(\nu) &= \nu P'_k(\nu) - P'_{k-1}(\nu) \\ kP_{k-1}(\nu) &= P'_k(\nu) - \nu P'_{k-1}(\nu) \end{aligned} \right\} (\nu^2 - 1) P'_k(\nu) = \nu k P_k(\nu) - k P_{k-1}(\nu)$$

Series Expansion of the Disturbing Function

$$R_j \triangleq Gm_j \left(\frac{1}{r_{2/j}} - \frac{1}{r_{j/1}^3} \mathbf{r}_{2/1} \cdot \mathbf{r}_{j/1} \right) = \frac{Gm_j}{r_{j/1}} \left[1 + \sum_{k=0}^{\infty} P_k(\cos \alpha_j) \left(\frac{r_{2/1}}{r_{j/1}} \right)^k \right]$$

$$\begin{aligned} \mathcal{I} \frac{d^2}{dt^2} \mathbf{r}_{2/1} + \frac{\mu}{\|\mathbf{r}_{2/1}\|^3} \mathbf{r}_{2/1} &= \nabla \sum_{j=3}^n R_j \\ &= G \sum_{j=3}^n \frac{m_j}{r_{j/1}^2} \sum_{k=1}^{\infty} \left(\frac{r_{2/1}}{r_{j/1}} \right)^k \left[P'_{k+1}(\cos \alpha_j) \frac{\mathbf{r}_{j/1}}{r_{j/1}} - P'_k(\cos \alpha_j) \frac{\mathbf{r}_{2/1}}{r_{2/1}} \right] \end{aligned}$$

Which is Dominant: m_1 or m_3 ?



$$\frac{r_{2/3}}{r_{3/1}} = \left[1 - 2 \frac{r_{2/1}}{r_{3/1}} \cos \alpha + \left(\frac{r_{2/1}}{r_{3/1}} \right)^2 \right]^{\frac{1}{2}}$$

$$\cos \beta = \frac{r_{3/1}}{r_{2/3}} - \frac{r_{2/1}}{r_{2/3}} \cos \alpha$$

$$m_1 \text{ dominant : } \frac{\mathcal{I} d^2}{dt^2} \mathbf{r}_{2/1} + \frac{G(m_1 + m_2)}{\|\mathbf{r}_{2/1}\|^3} \mathbf{r}_{2/1} = -Gm_3 \left(\frac{\mathbf{r}_{3/1}}{\|\mathbf{r}_{3/1}\|^3} + \frac{\mathbf{r}_{2/3}}{\|\mathbf{r}_{2/3}\|^3} \right)$$

$$m_3 \text{ dominant : } \frac{\mathcal{I} d^2}{dt^2} \mathbf{r}_{2/3} + \underbrace{\frac{G(m_2 + m_3)}{\|\mathbf{r}_{2/3}\|^3} \mathbf{r}_{2/3}}_{\text{Central}} = -Gm_1 \underbrace{\left(\frac{\mathbf{r}_{2/1}}{\|\mathbf{r}_{2/1}\|^3} + \frac{\mathbf{r}_{1/3}}{\|\mathbf{r}_{1/3}\|^3} \right)}_{\text{Perturbing}}$$

Sphere of Influence

$$\left(\frac{\|\mathbf{f}_{\text{perturbing}}\|}{\|\mathbf{f}_{\text{central}}\|}\right)_{m_1} = \frac{Gm_3 \left[\left(\frac{r_{2/3}}{r_{2/3}^3} + \frac{r_{3/1}}{r_{3/1}^3} \right) \cdot \left(\frac{r_{2/3}}{r_{2/3}^3} + \frac{r_{3/1}}{r_{3/1}^3} \right) \right]^{\frac{1}{2}}}{G(m_1 + m_2)r_{2/1}^{-2}}$$

$$= \frac{m_3}{m_2 + m_1} \frac{(r_{2/1}/r_{3/1})^2}{(r_{2/3}/r_{3/1})^2} \left[1 + \left(\frac{r_{2/3}}{r_{3/1}} \right)^4 - 2 \left(\frac{r_{2/3}}{r_{3/1}} \right) \left(1 - \frac{r_{2/1}}{r_{3/1}} \cos \alpha \right) \right]^{\frac{1}{2}}$$

$$\left(\frac{\|\mathbf{f}_{\text{perturbing}}\|}{\|\mathbf{f}_{\text{central}}\|}\right)_{m_3} = \frac{m_1}{m_2 + m_3} \left(\frac{r_{2/1}}{r_{3/1}} \right)^{-2} \left(\frac{r_{2/3}}{r_{3/1}} \right)^2 \left[1 + \left(\frac{r_{2/1}}{r_{3/1}} \right)^4 - 2 \left(\frac{r_{2/1}}{r_{3/1}} \right)^2 \cos \alpha \right]^{\frac{1}{2}}$$

$$\text{Intersection : } \left(\frac{r_{2/1}}{r_{3/1}} \right)^4 = \frac{m_1(m_1 + m_2)}{m_3(m_2 + m_3)} \left(\frac{r_{2/3}}{r_{3/1}} \right)^4 \left[\frac{1 + \left(\frac{r_{2/1}}{r_{3/1}} \right)^4 - 2 \left(\frac{r_{2/1}}{r_{3/1}} \right)^2 \cos \alpha}{1 + \left(\frac{r_{2/3}}{r_{3/1}} \right)^4 - 2 \left(\frac{r_{2/3}}{r_{3/1}} \right) \left(1 - \frac{r_{2/1}}{r_{3/1}} \cos \alpha \right)} \right]^{\frac{1}{2}}$$

$$\left(\frac{r_{2/1}}{r_{3/1}} \right) \approx \left(\frac{m_1}{m_3} \right)^{\frac{2}{5}} \Rightarrow r_{\text{SOI}} \approx a_{\text{planet}} \left(\frac{m_{\text{planet}}}{m_{\text{sun}}} \right)^{\frac{2}{5}}$$

Variation of Parameters (Orbital Elements)

$$\mathbf{h} = \mathbf{r} \times \mathbf{v}$$

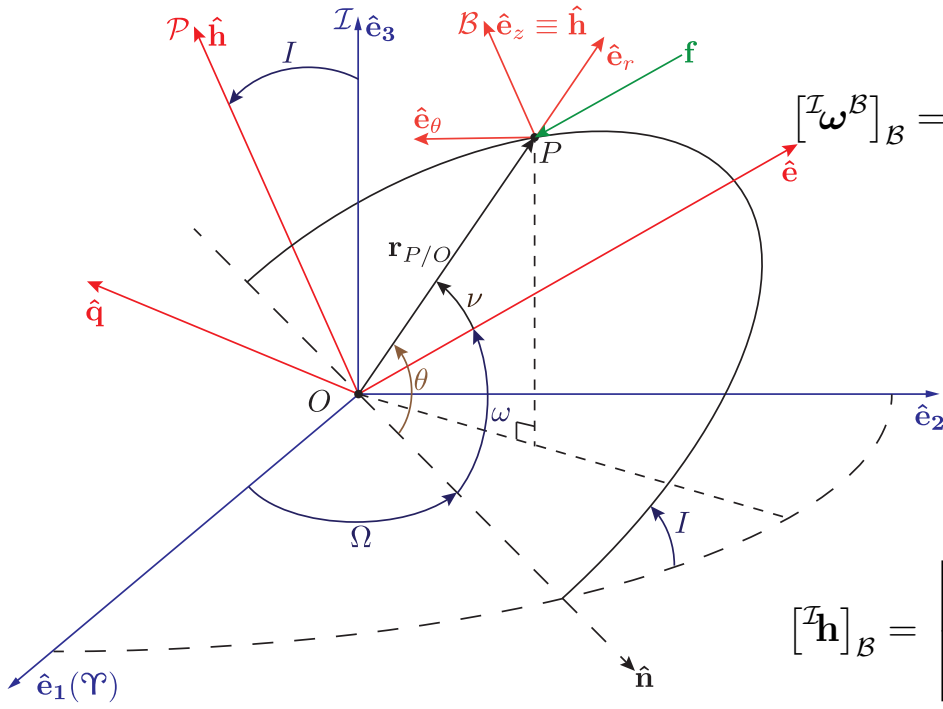
$$\mathcal{I} \frac{d}{dt} \mathbf{h} = \mathbf{r} \times \mathbf{f}$$

$$\mathbf{e} = \frac{\mathbf{v} \times \mathbf{h}}{\mu} - \frac{\mathbf{r}}{\|\mathbf{r}\|}$$

$$\mathcal{I} \frac{d^2}{dt^2} \mathbf{r} = \mathcal{I} \frac{d}{dt} \mathbf{v} = -\frac{\mu}{\|\mathbf{r}\|^3} \mathbf{r} + \mathbf{f}$$

$$\mathcal{I} \frac{d}{dt} \mathbf{e} = \frac{1}{\mu} (\mathbf{f} \times \mathbf{h} + \mathbf{v} \times (\mathbf{r} \times \mathbf{f}))$$

Variation of Parameters Reference Frames



$$\mathcal{I}\omega^B = \dot{\Omega}\hat{e}_3 + \dot{I}\hat{n} + \dot{\theta}\hat{h}$$

$$[\mathcal{I}\omega^B]_B = \begin{bmatrix} \dot{I} \cos(\theta) + \dot{\Omega} \sin(I) \sin(\theta) \\ -\dot{I} \sin(\theta) + \dot{\Omega} \sin(I) \cos(\theta) \\ \dot{\Omega} \cos(I) + \dot{\theta} \end{bmatrix}_B$$

$$[\mathbf{r}]_B = \begin{bmatrix} r \\ 0 \\ 0 \end{bmatrix}_B \quad [\mathcal{T}_v]_B = \begin{bmatrix} v_r \\ v_\theta \\ 0 \end{bmatrix}_B$$

$$[\mathbf{f}]_B = \begin{bmatrix} f_r \\ f_\theta \\ f_h \end{bmatrix}_B$$

$$[\mathcal{T}_h]_B = \begin{bmatrix} 0 \\ 0 \\ h \end{bmatrix}_B \quad [\mathbf{e}]_B = \begin{bmatrix} e \cos \nu \\ -e \sin \nu \\ 0 \end{bmatrix}_B$$

Gauss's Perturbation Equations (the setup)

$$\mathcal{I} \frac{d}{dt} \mathbf{h} = {}^B \frac{d}{dt} \mathbf{h} + \mathcal{I}\omega^B \times \mathbf{h} = \mathbf{r} \times \mathbf{f} \Rightarrow$$

$$\begin{bmatrix} 0 \\ 0 \\ \dot{h} \end{bmatrix}_B + \begin{bmatrix} h \left(-\dot{I} \sin(\theta) + \dot{\Omega} \sin(I) \cos(\theta) \right) \\ -h \left(\dot{I} \cos(\theta) + \dot{\Omega} \sin(I) \sin(\theta) \right) \\ 0 \end{bmatrix}_B = \begin{bmatrix} 0 \\ -f_h r \\ f_\theta r \end{bmatrix}_B$$

$$\mathcal{I} \frac{d}{dt} \mathbf{e} = {}^B \frac{d}{dt} \mathbf{e} + \mathcal{I}\omega^B \times \mathbf{e} = \frac{1}{\mu} (\mathbf{f} \times \mathbf{h} + \mathbf{v} \times (\mathbf{r} \times \mathbf{f})) \Rightarrow$$

$$\begin{bmatrix} -e(\dot{\omega} - \dot{\theta}) \sin(\omega - \theta) + \dot{e} \cos(\omega - \theta) \\ e(\dot{\omega} - \dot{\theta}) \cos(\omega - \theta) + \dot{e} \sin(\omega - \theta) \\ 0 \end{bmatrix}_B + \begin{bmatrix} -e(\dot{\Omega} \cos(I) + \dot{\theta}) \sin(\omega - \theta) \\ e(\dot{\Omega} \cos(I) + \dot{\theta}) \cos(\omega - \theta) \\ e(\dot{I} \sin(\omega) - \dot{\Omega} \sin(I) \cos(\omega)) \end{bmatrix}_B = \frac{1}{\mu} \left(\begin{bmatrix} f_\theta h \\ -f_r h \\ 0 \end{bmatrix}_B + \begin{bmatrix} f_\theta r v_\theta \\ -f_\theta r v_r \\ -f_h r v_r \end{bmatrix}_B \right)$$

Gauss's Perturbation Equations (the solution)

$$\begin{aligned}
 \dot{I} &= \frac{f_h r}{h} \cos(\theta) & \dot{e} &= \frac{e f_\theta}{h} r \sin^2(\nu) + \frac{f_r h}{\mu} \sin(\nu) + \frac{2 f_\theta}{\mu} h \cos(\nu) \\
 \dot{\Omega} &= \frac{f_h r \sin(\theta)}{h \sin(I)} & \dot{\omega} &= -\frac{f_h r \sin(\theta)}{h \tan(I)} - \frac{f_\theta r}{2h} \sin(2\nu) - \frac{f_r h}{e\mu} \cos(\nu) + \frac{2 f_\theta h}{e\mu} \sin(\nu) \\
 \dot{h} &= f_\theta r & \frac{h}{r^2} &= \dot{\Omega} \cos(I) + \dot{\theta}
 \end{aligned}$$

$$\dot{a} = \frac{2a^2}{h} [e \sin \nu f_r + (1 + e \cos(\nu)) f_\theta]$$

Gauss's Perturbation Equations (other versions)

$$\begin{aligned}
 \frac{d\Omega}{dt} &= \frac{r \sin \theta}{h \sin i} a_{dh} \\
 \frac{di}{dt} &= \frac{r \cos \theta}{h} a_{dh} \\
 \frac{d\omega}{dt} &= \frac{1}{he} [-p \cos f a_{dr} + (p+r) \sin f a_{d\theta}] - \frac{r \sin \theta \cos i}{h \sin i} a_{dh} \\
 \frac{da}{dt} &= \frac{2a^2}{h} \left(e \sin f a_{dr} + \frac{p}{r} a_{d\theta} \right) \\
 \frac{de}{dt} &= \frac{1}{h} \{ p \sin f a_{dr} + [(p+r) \cos f + re] a_{d\theta} \} \\
 \frac{dM}{dt} &= n + \frac{b}{ahe} [(p \cos f - 2re) a_{dr} - (p+r) \sin f a_{d\theta}]
 \end{aligned}$$

Battin (1999) Eq. 10.41

NB: $f \equiv \nu$, $p \equiv \ell$
 $(a_{dr}, a_{d\theta}, a_{dh}) \equiv (f_r, f_\theta, f_h)$

$$\begin{aligned}
 \frac{da}{dt} &= \frac{2}{n\sqrt{1-e^2}} \left\{ e \sin(\nu) F_R + \frac{\ell}{r} F_S \right\} \\
 \frac{de}{dt} &= \frac{\sqrt{1-e^2}}{na} \left\{ \sin(\nu) F_R + \left(\cos(\nu) + \frac{e + \cos(\nu)}{1 + e \cos(\nu)} \right) F_S \right\} \\
 \frac{di}{dt} &= \frac{r \cos(u)}{na^2 \sqrt{1-e^2}} F_W \\
 \frac{d\Omega}{dt} &= \frac{r \sin(u)}{na^2 \sqrt{1-e^2} \sin(i)} F_W \\
 \frac{d\omega}{dt} &= \frac{\sqrt{1-e^2}}{nae} \left\{ -\cos(\nu) F_R + \sin(\nu) \left(1 + \frac{r}{p} \right) F_S \right\} - \frac{r \cot(i) \sin(u)}{h} F_W \\
 \frac{dM_o}{dt} &= \frac{1}{na^2 e} \left\{ (p \cos(\nu) - 2er) F_R - (p+r) \sin(\nu) F_S \right\} - \frac{dn}{dt} (t - t_o)
 \end{aligned}$$

Vallado (2013) Eq. 9-24

NB: $p \equiv \ell$
 $(F_R, F_S, F_W) \equiv (f_r, f_\theta, f_h)$